

Description

The DigiFlex® Performance™ (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The drive can be configured for a variety of external command signals. Commands can also be configured using the drive's built-in Motion Engine, an internal motion controller used with distributed motion applications. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

This DP Series drive features a CANopen interface for networking and a RS-232 interface for drive configuration and setup. Drive commissioning is accomplished using DriveWare® 7, available for download at www.a-m-c.com.

All drive and motor parameters are stored in non-volatile memory. The DPC Series Hardware Installation Manual is available for download at www.a-m-c.com.

Power Range

Peak Current	60 A (42.4 A _{RMS})
Continuous Current	30 A (21.2 A _{RMS})
Supply Voltage	200 - 480 VAC



Features

- ▲ Follows the CAN in Automation (CiA) 301 Communications Profile and 402 Device Profile
- ▲ Four Quadrant Regenerative Operation
- ▲ Space Vector Modulation (SVM) Technology
- ▲ Fully Digital State-of-the-art Design
- ▲ Programmable Gain Settings
- ▲ Fully Configurable Current, Voltage, Velocity and Position Limits
- ▲ PIDF Velocity Loop
- ▲ PID + FF Position Loop
- ▲ Compact Size, High Power Density
- ▲ 16-bit Analog to Digital Hardware
- ▲ Built-in brake/shunt regulator
- ▲ On-the-Fly Mode Switching
- ▲ On-the-Fly Gain Set Switching

MODES OF OPERATION

- Profile Current
- Profile Velocity
- Profile Position
- Interpolated Position Mode (PVT)

COMMAND SOURCE

- ±10 V Analog
- PWM and Direction
- Encoder Following
- Over the Network
- Sequencing
- Indexing
- Jogging

FEEDBACK SUPPORTED

- ±10 VDC Position
- Halls
- Incremental Encoder
- Auxiliary Incremental Encoder
- Tachometer (±10 VDC)

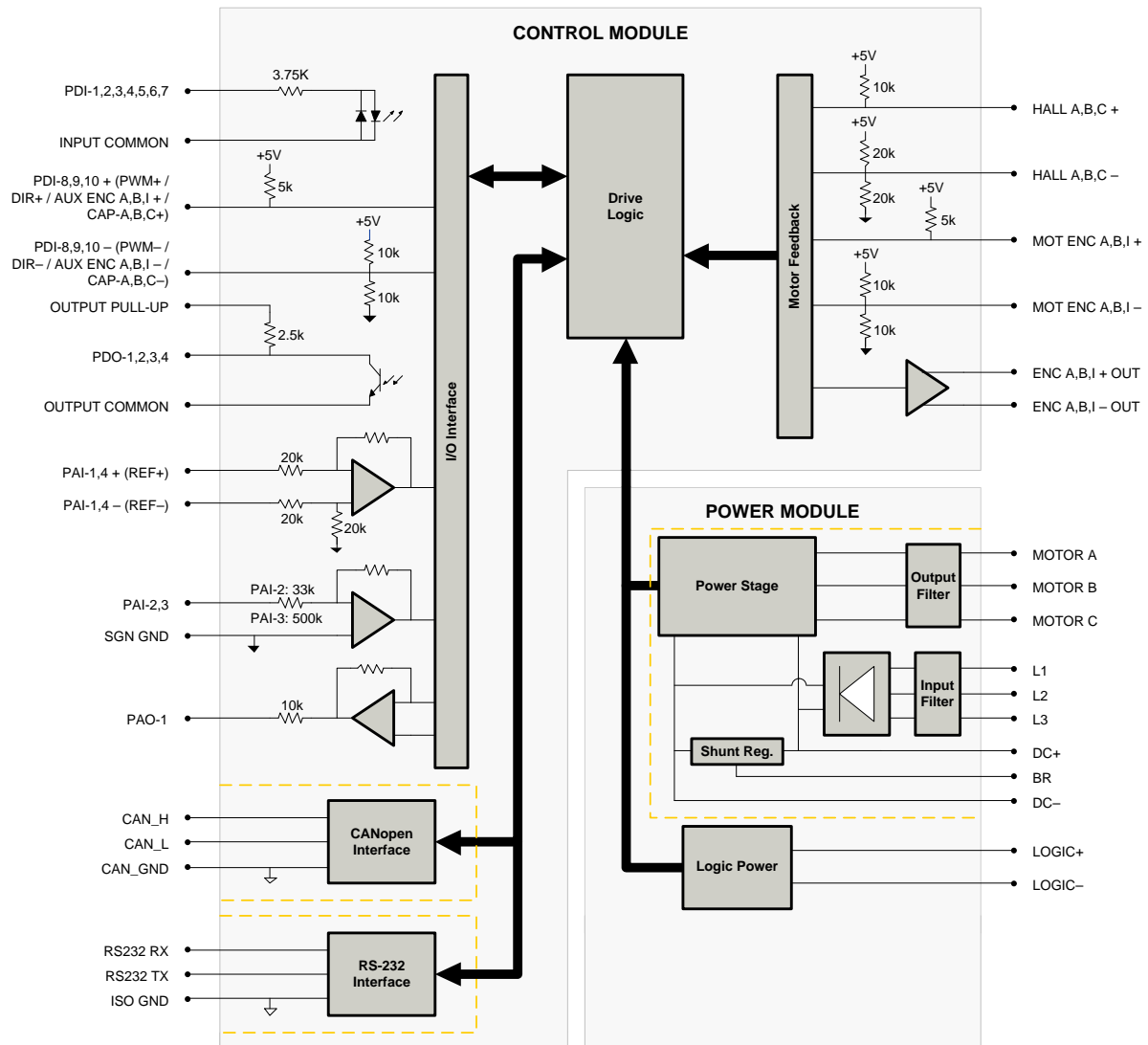
INPUTS/OUTPUTS

- 3 High Speed Captures
- 4 Programmable Analog Inputs (16-bit/12-bit Resolution)
- 1 Programmable Analog Output (10-bit Resolution)
- 3 Programmable Digital Inputs (Differential)
- 7 Programmable Digital Inputs (Single-Ended)
- 4 Programmable Digital Outputs (Single-Ended)

COMPLIANCES & AGENCY APPROVALS

- CE Class A (LVD)
- CE Class A (EMC)
- RoHS II

BLOCK DIAGRAM



Information on Approvals and Compliances



Compliant with European EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 for Emissions, Class A and EN 61000-6-2:2005 for Immunity, Performance Criteria A).
LVD requirements of Directive 2006/95/EC (specifically, EN 60204-1:2004, a Low Voltage Directive to protect users from electrical shock).



The RoHS II Directive 2011/65/EU restricts the use of certain substances including lead, mercury, cadmium, hexavalent chromium and halogenated flame retardants PBB and PBDE in electronic equipment.

SPECIFICATIONS

Description		Units	Power Specifications	Value
Rated Voltage		VAC (VDC)	480 (678)	
AC Supply Voltage Range		VAC	200 - 480	
AC Supply Minimum		VAC	180	
AC Supply Maximum		VAC	528	
AC Input Phases		-	3	
AC Supply Frequency		Hz	50 - 60	
DC Supply Voltage Range ¹		VDC	255 - 747	
DC Bus Over Voltage Limit		VDC	850	
DC Bus Under Voltage Limit		VDC	230	
Logic Supply Voltage		VDC	20 - 30 (@ 850 mA)	
Maximum Peak Output Current ²		A (Arms)	60 (42.4)	
Maximum Continuous Output Current		A (Arms)	30 (21.2)	
Max. Continuous Output Power @ Rated Voltage ³		W	13680	
Max. Continuous Power Dissipation @ Rated Voltage		W	720	
Internal Bus Capacitance		µF	330	
External Shunt Resistor Minimum Resistance ⁴		Ω	40	
Minimum Load Inductance (Line-To-Line) ⁵		µH	3000	
Switching Frequency		kHz	10	
Maximum Output PWM Duty Cycle		%	100	
Low Voltage Supply Outputs		-	+5 VDC (250 mA)	
Description		Units	Control Specifications	Value
Communication Interfaces		-	CANopen (RS-232 for configuration)	
Command Sources		-	±10 V Analog, Encoder Following, Over the Network, PWM and Direction, Sequencing, Indexing, Jogging	
Feedback Supported		-	±10 VDC Position, Auxiliary Incremental Encoder, Halls, Incremental Encoder, Tachometer (±10 VDC)	
Commutation Methods		-	Sinusoidal, Trapezoidal	
Modes of Operation		-	Profile Current, Profile Velocity, Profile Position, Interpolated Position Mode (PVT)	
Motors Supported		-	Closed Loop Vector, Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless)	
Hardware Protection		-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage	
Programmable Digital Inputs/Outputs (PDIs/PDOs)		-	10/4	
Programmable Analog Inputs/Outputs (PAIs/PAOs)		-	4/1	
Primary I/O Logic Level		-	24 VDC	
Current Loop Sample Time		µs	100	
Velocity Loop Sample Time		µs	200	
Position Loop Sample Time		µs	200	
Maximum Encoder Frequency		MHz	20 (5 pre-quadrature)	
Internal Shunt Regulator		-	Yes	
Internal Shunt Resistor		-	No	
Description		Units	Mechanical Specifications	Value
Agency Approvals		-	CE Class A (EMC), CE Class A (LVD), RoHS II	
Size (H x W x D)		mm (in)	300.5 x 232.1 x 139.3 (11.8 x 9.1 x 5.5)	
Weight		g (oz)	6174 (217.8)	
Heatsink (Base) Temperature Range ⁶		°C (°F)	0 - 75 (32 - 167)	
Storage Temperature Range		°C (°F)	-40 - 85 (-40 - 185)	
Form Factor		-	Panel Mount	
Cooling System		-	Natural Convection	
IP Rating		-	IP10	
+24V LOGIC Connector		-	2-port, 5.08 mm spaced, enclosed, friction lock header	
AUX COMM Connector		-	3-pin, 2.5 mm spaced, enclosed, friction lock header	
AUX ENCODER Connector		-	15-pin, high-density, male D-sub	
COMM Connector		-	Shielded, dual RJ-45 socket with LEDs	
DC BUS Connector		-	4-port, 7.62 mm spaced, enclosed, friction lock header	
FEEDBACK Connector		-	15-pin, high-density, female D-sub	
I/O Connector		-	26-pin, high-density, female D-sub	
MOTOR POWER Connector		-	4-port, 7.62 mm spaced, enclosed, friction lock header	
POWER Connector		-	3-port, 7.62 mm spaced, enclosed, friction lock header	

Notes

- DC supply operation through the L1, L2, or L3 terminals will reduce peak/cont. current ratings by 30%. See installation manual for details.
- Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.
- $P = (\text{DC Rated Voltage}) \times (\text{Cont. RMS Current}) \times 0.95$.
- ADVANCED Motion Controls recommends using an external fuse in series with the shunt resistor. A 3 amp motor delay fuse is typical.
- Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
- Additional cooling and/or heatsink may be required to achieve rated performance.

PIN FUNCTIONS

+24V LOGIC - Logic Power Connector			
Pin	Name	Description / Notes	I/O
1	LOGIC PWR	Logic Supply Input	I
2	LOGIC GND	Logic Supply Ground	GND

AUX COMM - RS232 Communication Connector			
Pin	Name	Description / Notes	I/O
1	RS232 RX	Receive Line (RS-232)	I
2	RS232 TX	Transmit Line (RS-232)	O
3	ISO GND	Isolated Signal Ground	IGND

AUX ENCODER - Auxiliary Feedback Connector			
Pin	Name	Description / Notes	I/O
1	RESERVED	Reserved	-
2	RESERVED	Reserved	-
3	RESERVED	Reserved	-
4	PDI-8 + (PWM+ / AUX ENC A+ / CAP-B+)	Programmable Digital Input or PWM or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
5	PDI-8 - (PWM- / AUX ENC A- / CAP-B-)	Programmable Digital Input or PWM or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
6	PDI-9 + (DIR+ / AUX ENC B+ / CAP-C+)	Programmable Digital Input or Direction Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
7	PDI-9 - (DIR- / AUX ENC B- / CAP-C-)	Programmable Digital Input or Direction Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
8	PDI-10 + (AUX ENC I+ / CAP-A+)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
9	PDI-10 - (AUX ENC I- / CAP-A-)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
10	SGN GND	Signal Ground	SGND
11	SGN GND	Signal Ground	SGND
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-4 +	Differential Programmable Analog Input (12-bit Resolution)	I
15	PAI-4 -	Differential Programmable Analog Input (12-bit Resolution)	I

COMM - CAN Communication Connector			
Pin	Name	Description / Notes	I/O
1	CAN_H	CAN_H Line (Dominant High)	I
2	CAN_L	CAN_L Line (Dominant Low)	I
3	CAN_GND	CAN Ground	CGND
4	RESERVED	Reserved	-
5	RESERVED	Reserved	-
6	RESERVED	Reserved	-
7	CAN_GND	CAN Ground	CGND
8	RESERVED	Reserved	-

DC BUS - Power Connector			
Pin	Name	Description / Notes	I/O
1	DC-	Internal DC Bus Voltage (Can Be Used To Connect External Shunt Regulator)	I/O
2	BR	External Brake Resistor Connection	-
3	DC+	Brake Resistor DC+. Connection for brake resistor.	O
4	DC+	Internal DC Bus Voltage (Can Be Used To Connect External Shunt Regulator)	I/O

FEEDBACK - Feedback Connector			
Pin	Name	Description / Notes	I/O
1	HALL A+	Commutation Sensor Inputs	I
2	HALL B+		I
3	HALL C+		I
4	MOT ENC A+	Differential Encoder A Channel Input (For Single Ended Signals Use Only The Positive Input)	I
5	MOT ENC A-		I
6	MOT ENC B+	Differential Encoder B Channel Input (For Single Ended Signals Use Only The Positive Input)	I
7	MOT ENC B-		I
8	MOT ENC I+	Differential Encoder Index Input (For Single Ended Signals Use Only The Positive Input)	I
9	MOT ENC I-		I
10	HALL A-	Commutation Sensor Input (For Differential Signals Only)	I
11	HALL B-	Commutation Sensor Input (For Differential Signals Only)	I
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-3	Programmable Analog Input (12-bit Resolution)	I
15	HALL C-	Commutation Sensor Input (For Differential Signals Only)	I

I/O - Signal Connector			
Pin	Name	Description / Notes	I/O
1	PDO-1	Isolated Programmable Digital Output	O
2	OUTPUT COMMON	Digital Output Common	OGND
3	PDO-2	Isolated Programmable Digital Output	O
4	PAI-1 + (REF+)	Differential Programmable Analog Input or Reference Signal Input (16-bit Resolution)	I
5	PAI-1 - (REF-)		I
6	PAI-2	Programmable Analog Input (12-bit Resolution)	I
7	PAO-1	Programmable Analog Output (10-bit Resolution)	O
8	OUTPUT PULL-UP	Digital Output Pull-Up For User Outputs	I
9	PDI-5	Isolated Programmable Digital Input	I
10	PDO-3	Isolated Programmable Digital Output	O
11	PDI-1	Isolated Programmable Digital Input	I
12	PDI-2	Isolated Programmable Digital Input	I
13	PDI-3	Isolated Programmable Digital Input	I
14	PDO-4	Isolated Programmable Digital Output	O
15	INPUT COMMON	Digital Input Common (Can Be Used To Pull-Up Digital Inputs)	IGND
16	SGN GND	Signal Ground	SGND
17	PDI-4	Isolated Programmable Digital Input	I
18	PDI-6	Isolated Programmable Digital Input	I
19	PDI-7	Isolated Programmable Digital Input	I
20	ENC A+ OUT	Buffered Encoder Channel A Output	O
21	ENC A- OUT		O
22	ENC B+ OUT	Buffered Encoder Channel B Output	O
23	ENC B- OUT		O
24	ENC I+ OUT	Buffered Encoder Index Output	O
25	ENC I- OUT		O
26	SGN GND	Signal Ground	SGND

MOTOR POWER - Power Connector			
Pin	Name	Description / Notes	I/O
1	SHIELD	Motor cable shield. Internally connected to protective earth ground.	-
2	MOTOR C	Motor Phase C	O
3	MOTOR B	Motor Phase B	O
4	MOTOR A	Motor Phase A	O

POWER - Power Connector			
Pin	Name	Description / Notes	I/O
1	L3	AC Supply Input (Three Phase)	I
2	L2		I
3	L1		I

HARDWARE SETTINGS

Switch Functions

Switch	Description	Setting	
		On	Off
1	Bit 0 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
2	Bit 1 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
3	Bit 2 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
4	Bit 3 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
5	Bit 4 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
6	Bit 5 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
7	Bit 0 of drive CANopen bit rate setting. Does not affect RS-232 settings.	1	0
8	Bit 1 of drive CANopen bit rate setting. Does not affect RS-232 settings.	1	0

Additional Details

The drive can be configured to use the address and/or bit rate stored in non-volatile memory by setting the address and/or bit rate value to 0. Use the table below to map actual bit rates to a bit rate setting. Note that higher bit rates are possible when using the value stored in NVM.

Bit Rate (kbits/sec)	Value For Bit Rate Setting
Load from non-volatile memory	0
500	1
250	2
125	3

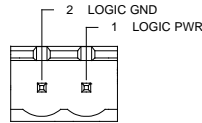
Jumper Settings

Jumper	Description	Configuration		
		Not Installed	Pins 1-2	Pins 2-3
J1	CAN bus termination. Install this jumper (2.54mm) on the last drive in a CAN network. This jumper is located on a 4-pin header adjacent to the RS-232 connector. It consists of the two pins furthest from the connector.	Non-terminating Node	Terminating Node	N/A
J2	Reserved.	-	-	N/A

MECHANICAL INFORMATION

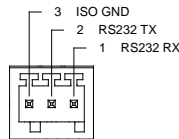
+24V LOGIC - Logic Power Connector

Connector Information		2-port, 5.08 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1757019
	Included with Drive	Yes



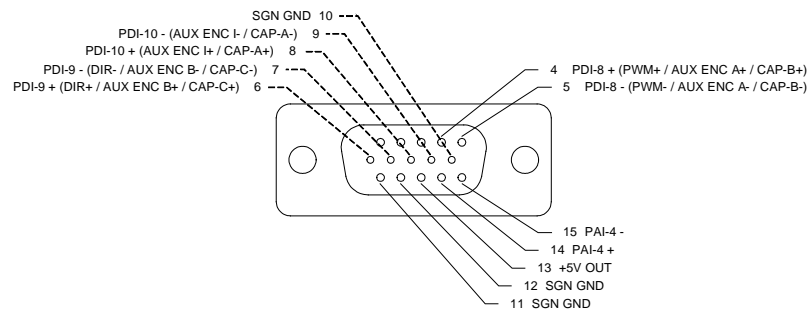
AUX COMM - RS232 Communication Connector

Connector Information		3-pin, 2.5 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix: Plug P/N 1881338
	Included with Drive	Yes



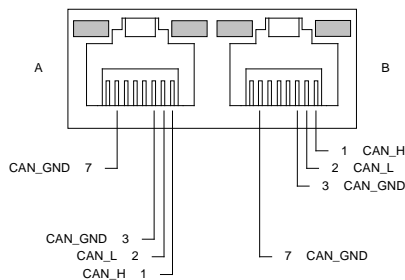
AUX ENCODER - Auxiliary Feedback Connector

Connector Information		15-pin, high-density, male D-sub
Mating Connector	Details	TYCO: Plug P/N 1658681-1; Housing P/N 5748677-1; Terminals P/N 1658686-2 (loose) or 1658686-1 (strip)
	Included with Drive	No



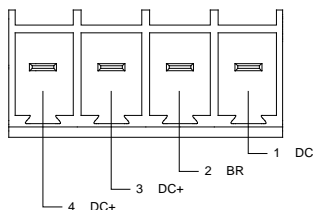
COMM - CAN Communication Connector

Connector Information		Shielded, dual RJ-45 socket with LEDs
Mating Connector	Details	AMP: Plug P/N 5-569552-3
	Included with Drive	No



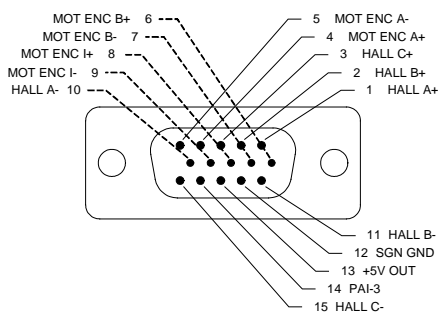
DC BUS - Power Connector

Connector Information		4-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1804920
	Included with Drive	Yes



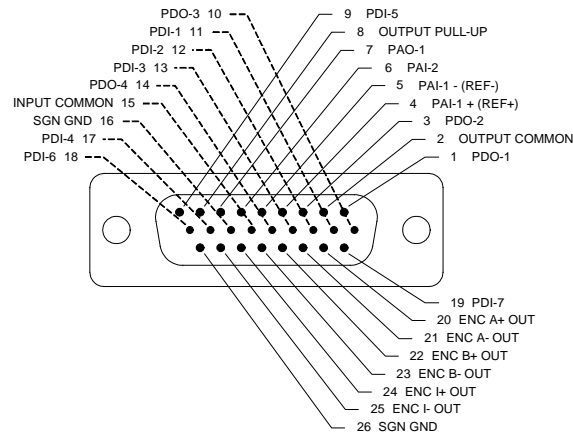
FEEDBACK - Feedback Connector

Connector Information		15-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 748364-1; Housing P/N 5748677-1; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
	Included with Drive	No



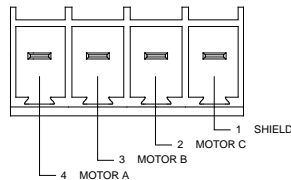
I/O - Signal Connector

Connector Information		26-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 1658671-1; Housing P/N 5748677-2; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
	Included with Drive	No



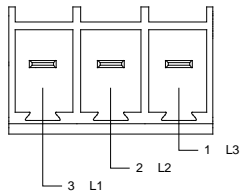
MOTOR POWER - Power Connector

Connector Information		4-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1804920
	Included with Drive	Yes

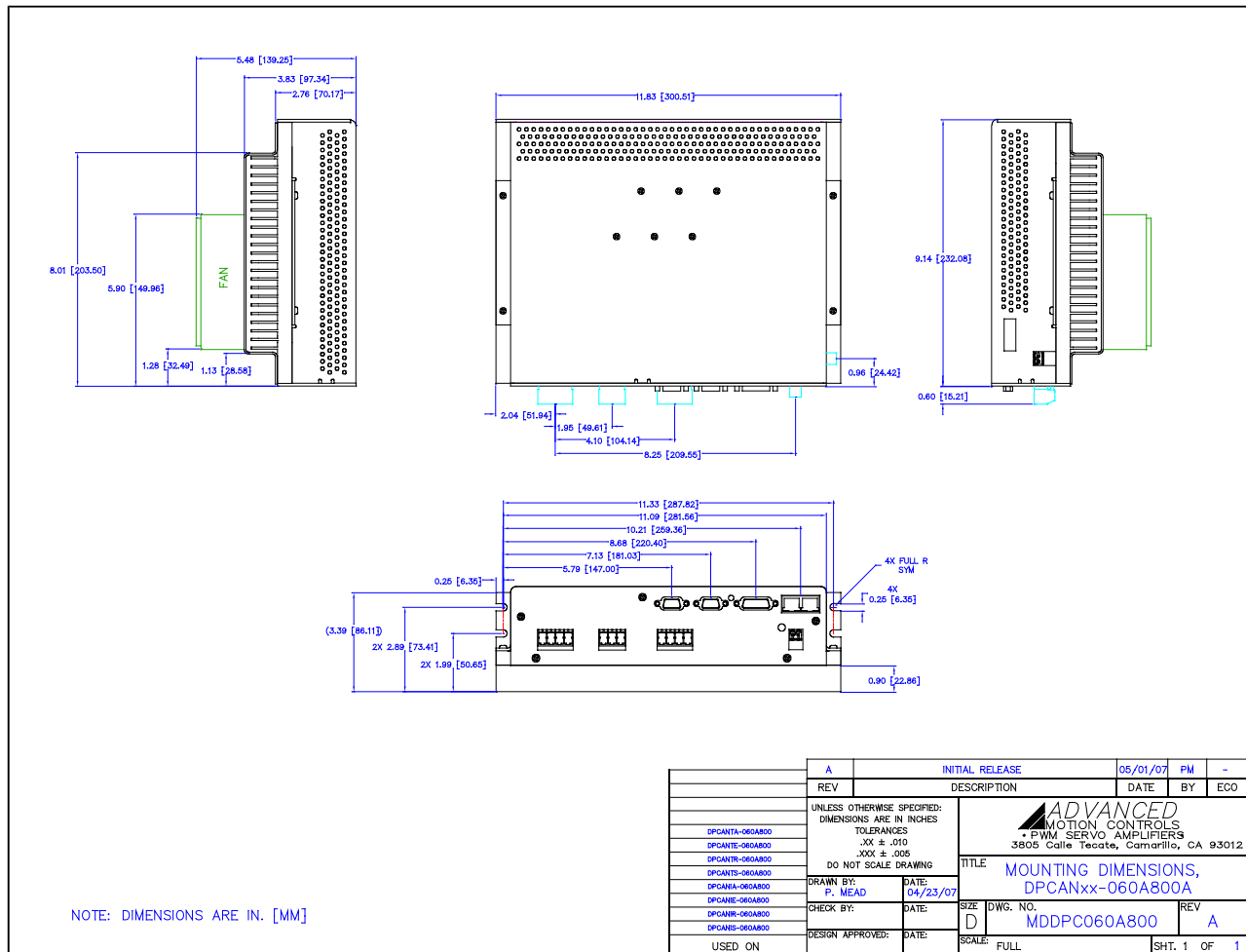


POWER - Power Connector

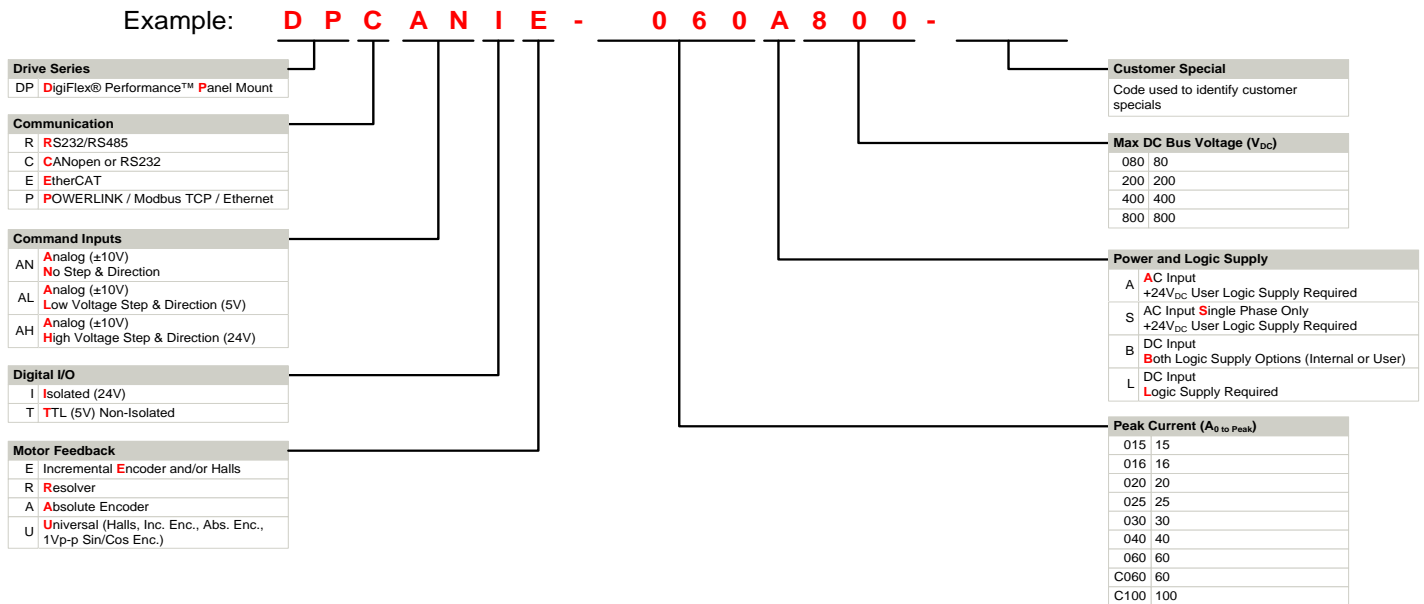
Connector Information		3-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1804917
	Included with Drive	Yes



MOUNTING DIMENSIONS



PART NUMBERING INFORMATION



DigiFlex® Performance™ series of products are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability. Feel free to contact Applications Engineering for further information and details.

Examples of Customized Products

- ▲ Optimized Footprint
- ▲ Private Label Software
- ▲ OEM Specified Connectors
- ▲ No Outer Case
- ▲ Increased Current Resolution
- ▲ Increased Temperature Range
- ▲ Custom Control Interface
- ▲ Integrated System I/O
- ▲ Tailored Project File
- ▲ Silkscreen Branding
- ▲ Optimized Base Plate
- ▲ Increased Current Limits
- ▲ Increased Voltage Range
- ▲ Conformal Coating
- ▲ Multi-Axis Configurations
- ▲ Reduced Profile Size and Weight

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.



All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.